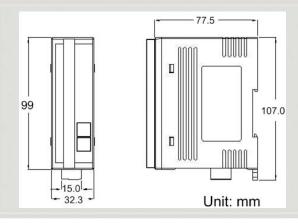


PWM module of CANopen Slave







CAN-2088C

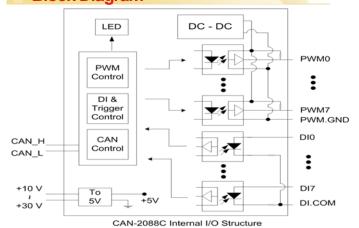
Dimensions

PWM (Pulse width modulation) is a powerful technique for controlling analog circuits. By using digital outputs, it can generate a waveform with variant duty cycle and frequency to control analog circuits. CAN-2088C, a CAN bus remote I/O modules with CANopen protocol, provides 8 PWM output channels and 8 digital inputs channels with high-speed counter function. It can be used to develop practical and economical analog control systems in the CANopen network.

Features

- Hardware-controlled PWM output.
- PWM output frequency: $0.2 \text{ Hz} \sim 500 \text{ kHz}$ with $0.1\% \sim 99.9\%$ duty cycle.
- PWM Output Modes: software trigger / hardware trigger.
- Trigger each PWM output individually or all PWM outputs synchronously.
- Support Burst output mode and Continue output mode.
- Provide 32-bit 500 kHz high-speed counter for each DI channel.
- Pass the validation of CANopen conformance test.
- Provide EDS file for CANopen master interface.

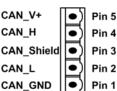
Block Diagram



I/O Pin & Wire Connection

Te	rminal	1	Pin Assignment	Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
	0	100	PO.0	Drive Relay	Relay On	Relay Off
	0	02	PO.1			III x nell pox
	0 0	03	PO.2		□⊕ POX	100
	Q 2	04	PO.3			
	50	05	PO.4	Resistance Load		
	0	06	PO.5		: □ POX	†
		07	PO.6		PO.GND	PO.GND
	0	08	PO.7			
	20	09	PO.GND	Input Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
	0	10	PO.GND	Relay Contact	Relay On	Relay Off
	[0]	11	DI.0		+# DDIX	+# DDIX
	0	12	DI.1		Relay Close DI.GND	Relay Open DI.GND
	20	13	DI.2	TTL/CMOS	Voltage > 10 V	Voltage < 4 V
	0	14	DI.3	Logic	Logic Power DIX Logic Level Low DI,GND	Logic Power DE DI X
	[o]	15	DI.4		Open Collector On	Open Collector Off
	0	16	DI.5	NPN		
	20	17	DI.6	Output	□ DI X DI.GND	□ DI X □ DI.GND
	N D	18	DI.7	PNP Output	Open Collector On	Open Collector Off
	20	19	DI.GND		DIX Del X	off€ DIX
	2 0	20	DI.GND	- Capar	ON ₹↓ DI.GND	DI.GND

CAN Pin & Baud Rate Rotary





rotary sv

	Owitch value	Dada Nate
	0	10 kbps
4	1	20 kbps
07	2	50 kbps
10	3	125 kbps
rate	4	250 kbps
witch	5	500 kbps
WILCI	6	800 kbps
	7	1000 kbps

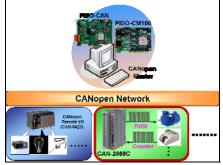
Switch Value Band Rate

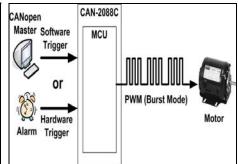


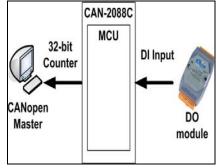
Hardware Specifications

CAN Interface							
Connector	5-pin screwed terminal block (CAN_GND, CAN_L, CAN_SHLD, CAN_H, CAN_V+)						
Baud Rate (bps)	10 k, 20 k, 50 k, 125 k, 250 k, 500 k, 800 k, 1 M						
Terminator Resistor	Switch for 120 Ω terminator resistor						
Node ID	1~99 selected by rotary switch						
Protocol	CANopen DS-301 ver4.02, DS-401 ver2.1						
No. of PDOs	10 Rx, 10 Tx (support dynamic PDO)						
PDO Mode	Event Triggered, Remotely requested, Cyclic and acyclic SYNC						
Error Control	Node Guarding protocol and Heartbeat Producer protocol						
Emergency Message	Yes						
PWM Interface							
Channels	8 (Source)						
Frequency Range	$0.2 \text{ Hz} \sim 500 \text{ kHz}$ (non-continuous, the min. unit of the high/low level signal is 1 us).						
PWM Mode	Continue mode, Burst mode, Hardware trigger mode, Software trigger mode						
ESD Protection	4 kV Contact for each channel						
DI Interface							
Channels	8 (Sink)						
Counter Frequency	32-bit, 500 kHz Max.						
ESD Protection	4 kV Contact for each channel						
LED							
Round LED	PWR LED, RUN LED, ERR LED						
I/O LED	8 LEDs as PWM, 8 LEDs as Digital Input, and 1 LED as terminal resister indicator						
Power							
Input range	Unregulated $+10 \sim +30 \text{ V}_{DC}$						
Power Consumption	3.5 W						
Mechanism							
Installation	DIN-Rail						
Dimensions	32.3 mm x 99 mm x 77.5 mm (W x L x H)						
Environment							
Operating Temp.	-25 ~ +75 °C						
Storage Temp.	-30 ~ +80 °C						
Humidity	10 ~ 90% RH, non-condensing						

Applications







Ordering Information Art.-Nr. 125295

CAN-2088C

CANopen Module of 8-channel PWM and 8-channel DI with High-speed Counters.